

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L23	50	("4421980" "4492119" "4888877" "5456021" "4348885" "4879572" "5606509" "5668628" "5680253" "5760734" "5861989" "5861964" "5973837" "5978111" "6020984" "4027210" "4275960" "4325125" "4367589" "4387370" "4403339" "4424589" "4425041" "4455667" "4471449" "4471823" "4519167" "4524282" "4796097" "4847555" "4847814" "4968140" "4973164" "5198738" "5257624" "5317314" "5400132" "5424535" "5508944" "5577501" "5612906" "5623305" "5625270" "5691527" "5690846" "5726366" "5726749" "5767515" "5783817" "5810005").pn.	USPAT	OR	OFF	2005/09/12 09:32
L24	2832267	(scale rule ruler graduation measurement calibration gauge)	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2005/09/12 09:34
L25	210663	((scan scanner scanning) near3 (device instrument apparatus appliance mechanism machine thing module element unit))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2005/09/12 09:34
L26	616219	(relative near3 (motion movement (change near3 position)))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2005/09/12 09:34
L27	103259	((evaluate evaluation evaluating judgement judging estimation estimating) near3 (module unit element part section))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2005/09/12 09:34
L28	73337	L24 and L25	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2005/09/12 09:34
L29	8212	L28 and L26	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2005/09/12 09:34

L30	434	L29 and L27	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2005/09/12 09:34
L31	11221	((angle slope (angular near3 position)) near3 (determin\$5 measur\$5) near3 (module unit element part section))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2005/09/12 09:34
L32	45234	((time chronologic chronological timing chronology) near3 (determin\$5 measur\$5) near3 (module unit element part section))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2005/09/12 09:36
L33	13	L30 and L31	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2005/09/12 09:34
L34	3	L33 and L32	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2005/09/12 09:34
L35	3	L34	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2005/09/12 09:40
L36	42	I23 and (I24 I25 I26 I27 I31 I32)	USPAT	OR	ON	2005/09/12 09:37
L37	1	I23 and I24 and I31 and I32	USPAT	OR	ON	2005/09/12 09:38
L38	37	I23 and I24	USPAT	OR	ON	2005/09/12 09:38
L39	25	I38 and I25	USPAT	OR	ON	2005/09/12 09:39
L40	2	I39 and I31	USPAT	OR	ON	2005/09/12 09:59
L41	1	I40 and I32	USPAT	OR	ON	2005/09/12 09:39
L42	0	L23 and ((angular angle tilt slope) near3 (position location)) and ((scanning scanner) near3 (device apparatus instrument mechanism module part section unit element)) and (((chronological chronology chronologic time timing) near3 (progression advancement progress)) with ((angular angle tilt slope) near3 (position location)))	USPAT	OR	ON	2005/09/12 09:45

L43	0	((angular angle tilt slope) near3 (position location)) and ((scanning scanner) near3 (device apparatus instrument mechanism module part section unit element)) and (((chronological chronology chronologic time timing) near3 (progression advancement progress)) with ((angular angle tilt slope) near3 (position location)))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2005/09/12 09:45
L44	1	((angular angle tilt slope) near3 (position location)) and ((scanning scanner) near3 (device apparatus instrument mechanism module part section unit element)) and (((chronological chronology chronologic time timing) near3 (progression advancement progress)) same ((angular angle tilt slope) near3 (position location)))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2005/09/12 09:47
L45	263	((angular angle tilt slope) near3 (position location)) and ((scanning scanner) near3 (device apparatus instrument mechanism module part section unit element)) and (((chronological chronology chronologic time timing) same ((change changing alter alteration altering move moving movement motion) with ((angular angle tilt slope) near3 (position location))))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2005/09/12 09:50
L46	118	((angular angle tilt slope) near3 (position location)) and ((scanning scanner) near3 (device apparatus instrument mechanism module part section unit element)) and (((chronological chronology chronologic time timing) with (change changing alter alteration altering move moving movement motion) with ((angular angle tilt slope) near3 (position location)))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2005/09/12 09:50
L47	106	((detect\$3 determin\$5 measur\$5) with ((relative related) near3 (angular angle) near3 position) with ((scanning scanner near3 (device apparatus mechanism instrument unit element))))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2005/09/12 10:45
L48	1	l47 and (determin\$5 with ((chronologic chronological time) near3 (progression advancement (rate near3 change))) near3 ((angular angle) near3 position) with ((scanning scanner near3 (device apparatus mechanism instrument unit element))))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2005/09/12 10:37
L49	1	l47 and (determin\$5 with ((chronologic chronological time) near3 (progression advancement (rate near3 change))) near3 ((angular angle) near3 position))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2005/09/12 10:36

L50	1	l47 and (determin\$5 with ((chronologic chronological time) near3 (progression advancement (rate near3 change))) near3 ((angular angle) near3 (position displacement)))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2005/09/12 10:37
L51	1	(determin\$5 with ((chronologic chronological time) near3 (progression advancement (rate near3 change))) near3 ((angular angle) near3 (position displacement)) with ((scanning scanner near3 (device apparatus mechanism instrument unit element))))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2005/09/12 10:38
L52	2	(determin\$5 with (((chronologic chronological time) near3 (progression advancement (rate near3 change))) (rate near3 change)) near3 ((angular angle) near3 (position displacement)) with ((scanning scanner near3 (device apparatus mechanism instrument unit element))))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2005/09/12 10:47
L53	2	l47 and l52	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2005/09/12 10:39
L54	2773	((detect\$3 determin\$5 measur\$5) with ((angular angle) near3 (position displacement))) same ((scanning scanner near3 (device apparatus mechanism instrument unit element)))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2005/09/12 10:50
L56	4	l54 and (determin\$5 with (((chronologic chronological time) near3 (progression advancement (rate near3 change))) (rate near3 change)) near3 ((angular angle) near3 (position displacement)))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2005/09/12 10:49
L57	65	(determin\$5 with (((chronologic chronological time) near3 (progression advancement (rate near3 change))) (rate near3 change)) near3 ((angular angle) near3 (position displacement)))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2005/09/12 10:49
L58	9	((detect\$3 determin\$5 measur\$5) with ((angular angle) near3 (position displacement))) and ((scanning scanner near3 (device apparatus mechanism instrument unit element))) and (determin\$5 with (((chronologic chronological time) near3 (progression advancement (rate near3 change))) (rate near3 change)) near3 ((angular angle) near3 (position displacement)))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2005/09/12 10:58

L59	3	l58 and ((position displacement) near3 (measur\$5 determin\$5) near3 (system device apparatus unit))	US-PGPUB; USPAT; USOCR; EPO; JPO; DERWENT ; IBM_TDB	OR	ON	2005/09/12 11:01
L60	1	("4631404" "6043482" "5294793" "5115573").pn. and ((angular angle) near3 (position displacement))	USPAT	OR	ON	2005/09/12 11:04
L61	2	("4631404" "6043482" "5294793" "5115573").pn. and (((relative related) near3 (position displacement)) with ((scanner scanning) near3 (device apparatus unit)))	USPAT	OR	ON	2005/09/12 11:06
L62	0	l61 and (((chronologic chronological time) near3 (progression advancement (rate near3 change))) (rate near3 change))	USPAT	OR	ON	2005/09/12 11:07
L63	0	l61 and (((angle angular) near3 (progression advancement (rate near3 change))) (rate near3 change))	USPAT	OR	ON	2005/09/12 11:07

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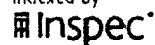
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IEEE STD IEEE Standard

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Barker, J.L.; Seiferth, J.C.;
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- ☐ 2. **Track while scan monopulse-a technique for improving angular accuracy**
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- ☐ 4. **Laser-ultrasonics three-dimensional imaging of advanced composite mat**
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- ☐ 5. **Model-based calibration of a range camera**
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8. **Effects of patient motion in coincidence studies on hybrid PET/SPECT sy**
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9. **A high resolution ultrasonic imaging system for the detection of cervical**
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12. **Autonomous robot learning: what can we take for free?**
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- ☐ 1. The scattering cross section of a composite cylinder, geometric optics
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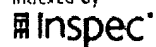
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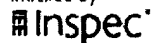
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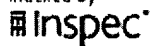
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